

CAPTURING THE EFFECT OF DATA COLLECTION PROTOCOL ON LAND-USE REGRESSION MODELS AND EXPOSURE SURFACES FOR ULTRAFINE PARTICLES, BLACK CARBON, AND NOISE

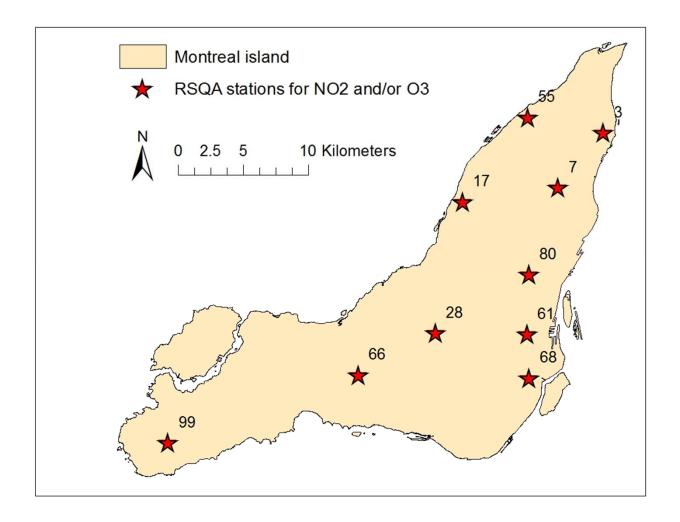
Laura Minet, Rick Liu, Marie-France Valois, Junshi Xu, Scott Weichenthal, and Marianne Hatzopoulou

marianne.hatzopoulou@utoronto.ca

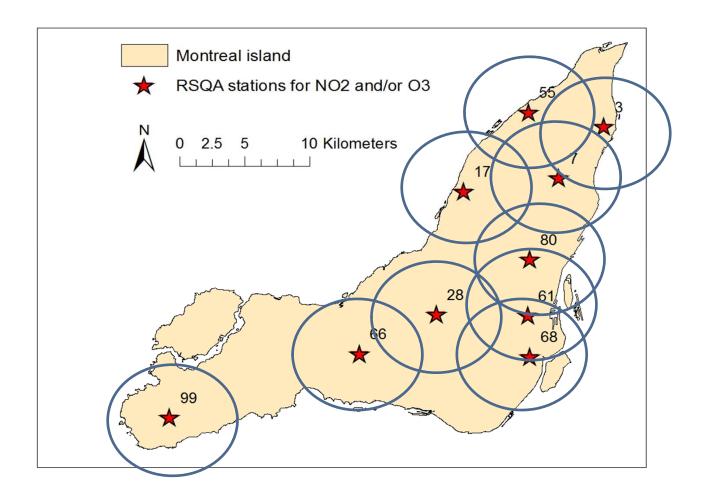




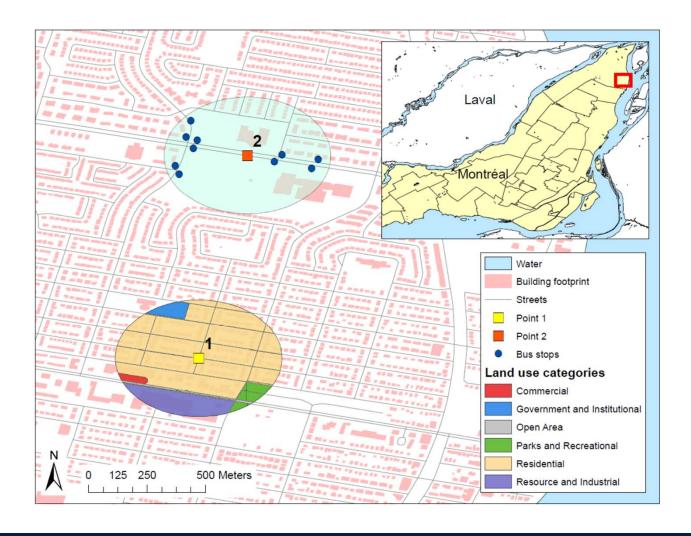
Land use regression (LUR)



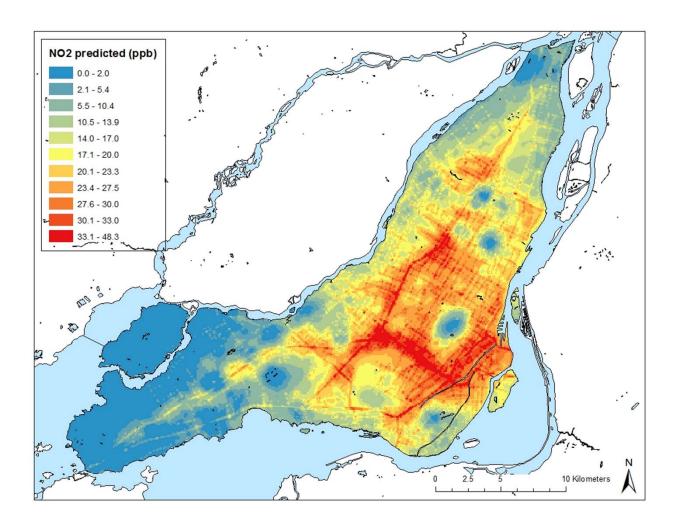
Land use regression (LUR)



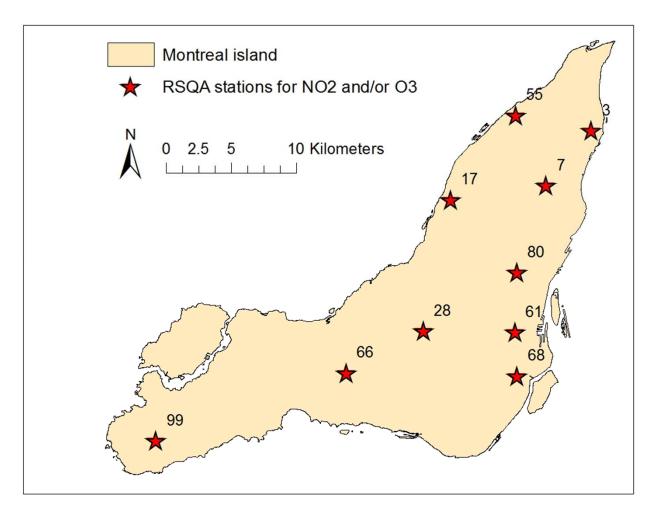
Land use regression (LUR)



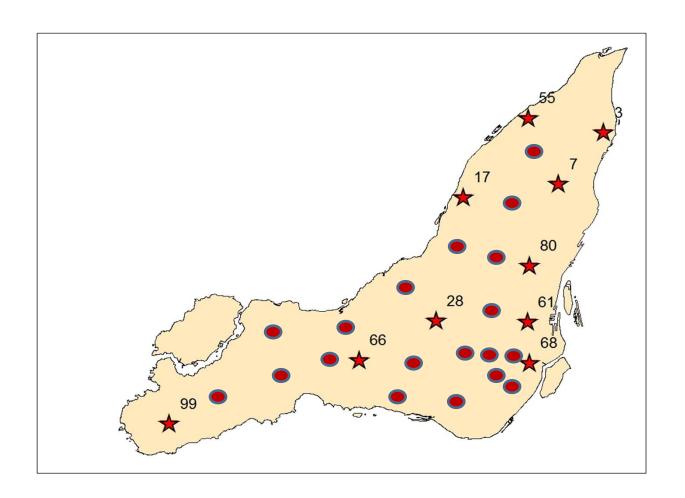
Exposure surface



Spatial variability and spatial coverage are important



Advances in portable air pollution devices enabled denser sampling campaigns



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Mobile sampling achieves unparalleled spatial coverage

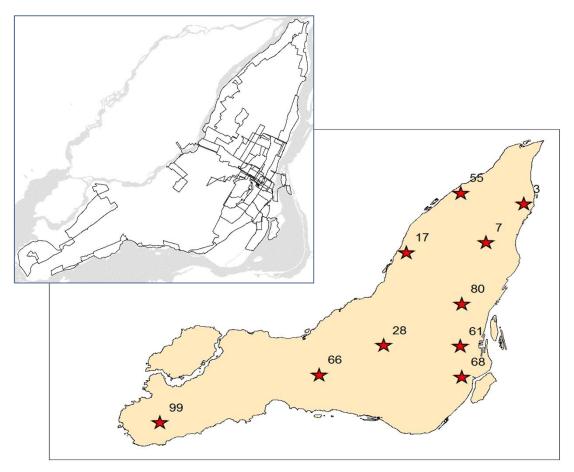


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Does the data collection protocol influence LUR models and associated exposure surfaces?



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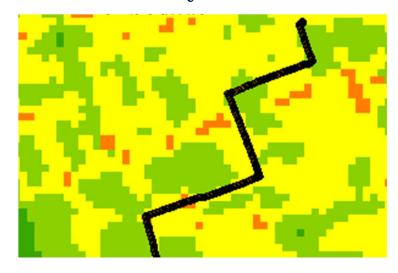
Short-term exposure estimation

Personal



Photo credit: Tyler Irving/U of T Engineering

Mobility-based



GPS intersecting exposure surface

How do mobility-based exposures compare with personal exposures?

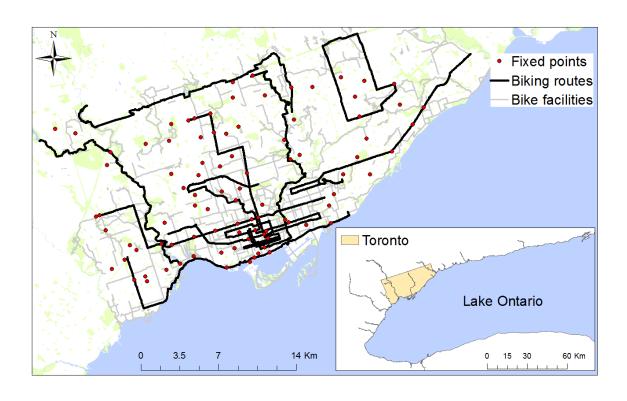
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1. Ultrafine Particles (UFP) and Black Carbon (BC) levels



❖ 92 fixed points: Average sampling:

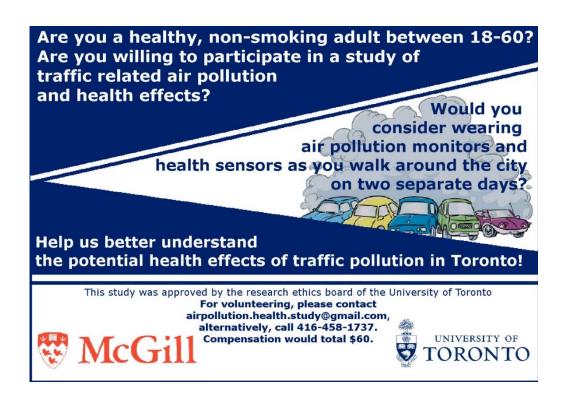
- 102 minutes
 - 5 visits
- 270 km of cycling routes/3,095 road segments:

Average sampling:

- 121 seconds
- 5 visits

Time block	Time
1	7 am to 11 am
2	11 am to 3 pm
3	3 pm to 7 pm

2. Panel study



- **❖** 1 visit:
 - 6 hours / day
 - 2 hours outdoors
- **❖** Total:
 - 43 participants
 - 63 visits

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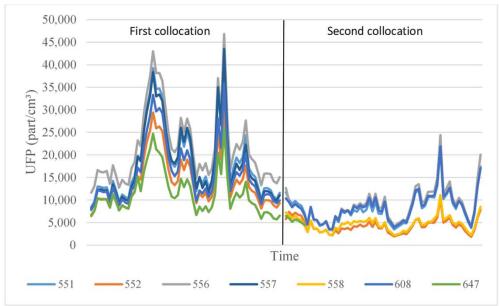
3. Equipment



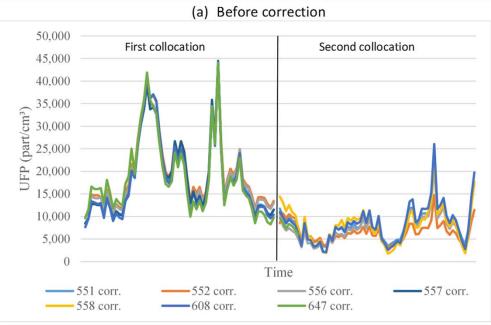
- **GPS**:
 - Garmin or Mobile app Strava
 - Time resolution: 1s
- **❖** <u>UFP:</u>
 - DiscMini
 - Time resolution: 1s
- **❖** BC:
 - MicroAethalometer
 - Time resolution: 30s (average of 30s)

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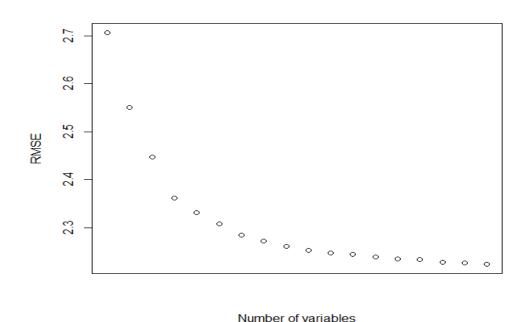
Collocation UFP

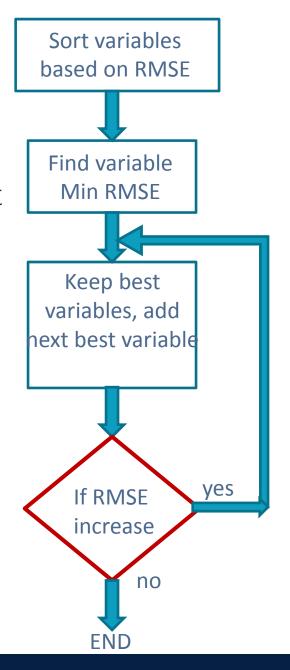


(b) After correction

LUR model development

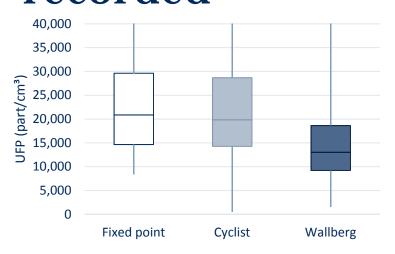
❖ A leave one out cross-validation (LOOCV) was applied to choose the best predictor variables in order to minimise the Root Mean Square Error (RMSE)

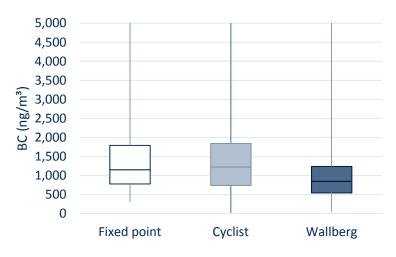


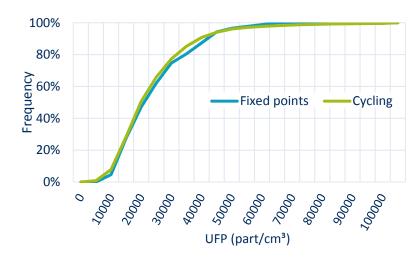


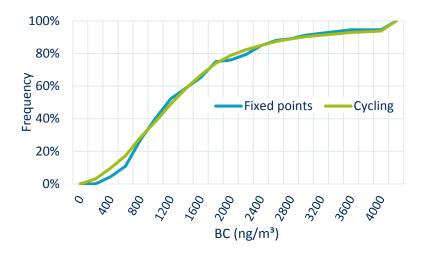
Results

Average UFP and BC concentrations recorded









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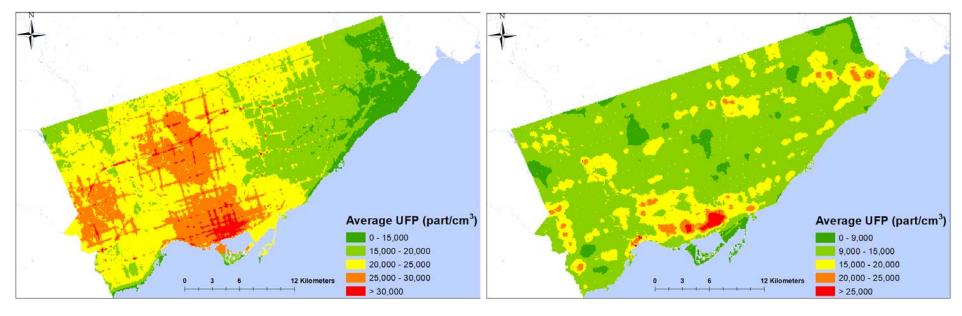
LUR models

	In(UFP)		In(BC)	
	Fixed points	Cycling	Fixed points	Cycling
Adjusted R ²	0.405	0.430	0.525	0.434

- ❖ R² ranges between 0.405 and 0.525
- ***** Various predictors

NOISE (LAeq)	Model 1	Model 1 modified
Adjusted R ²	0.6	0.44
N. of predictors	14	10

Exposure surfaces - UFP



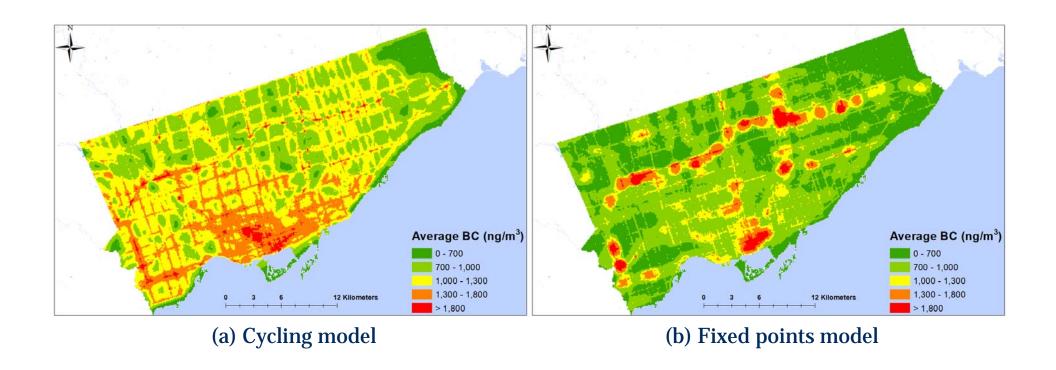
(a) Cycling model

(b) Fixed points model

Pearson correlation coefficient: 0.235

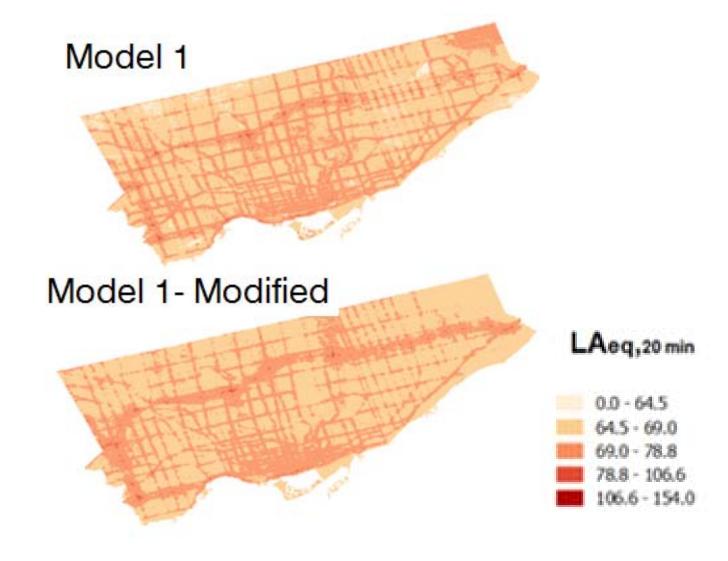
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Exposure surfaces - BC

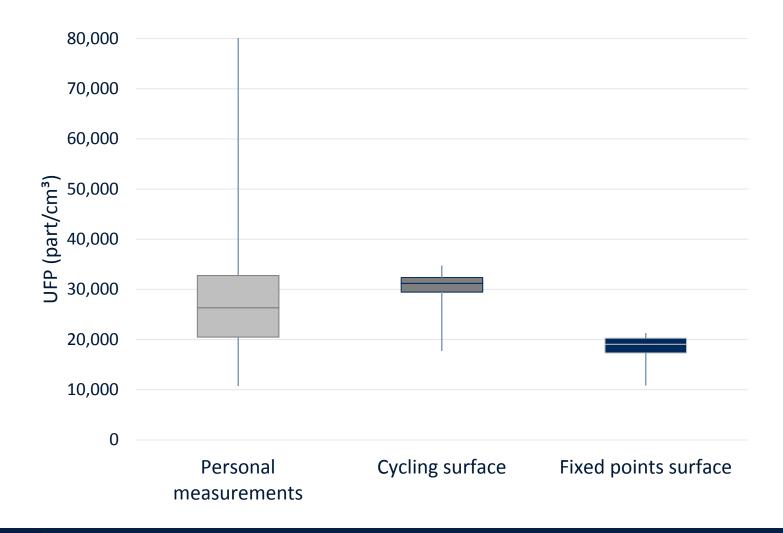


Pearson correlation coefficient: 0.5

Exposure surfaces – Noise (LAeq)



Comparison of the exposures - UFP



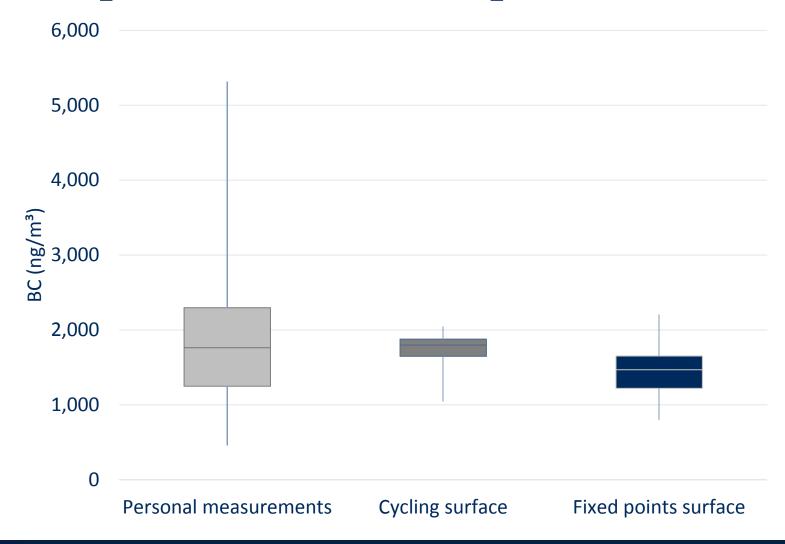
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Comparison of the exposures - BC



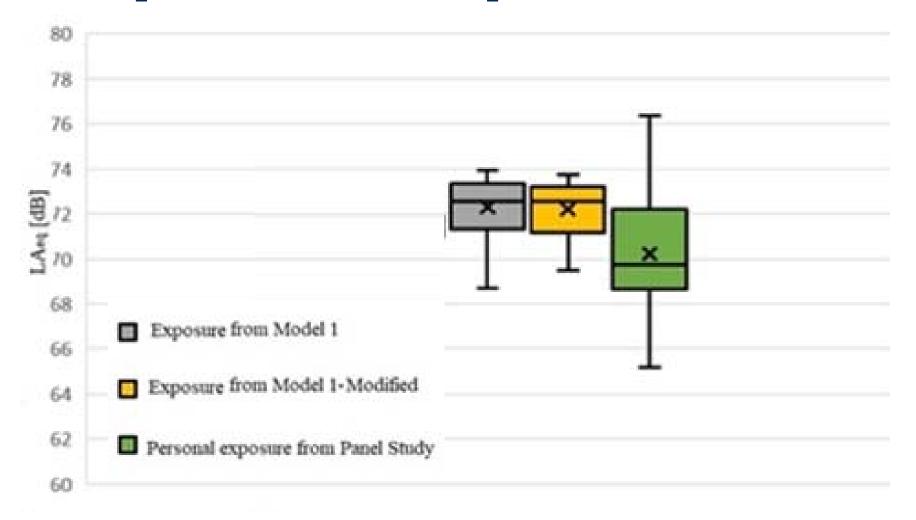
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Comparison of the exposures - Noise



Conclusions

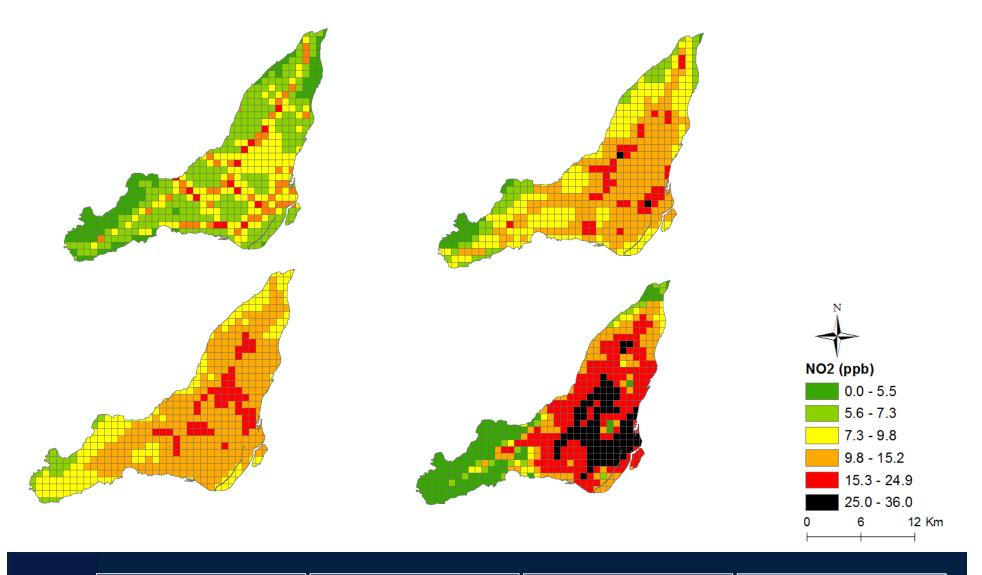
Different data collection protocols

Different LUR models and dissimilar exposure surfaces

Different short-term exposure estimations



NO₂ surfaces Dispersion-1 (a) Dispersion-2 (b) LUR-1 (c) LUR-2 (d)



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$OR\ for\ Prostate\ Cancer\\ NO_2\ surfaces\ Dispersion-1\ (a)\ Dispersion-2\ (b)\ LUR-1\ (c)\ LUR-2\ (d)$

